





## **Center of Mass**

#### Key Idea

When dealing with objects like a ball, tire, or flat-screen television, determining the center of mass (CM) is straightforward due to their symmetry. For example, throwing a ball as a projectile allows us to predict its motion, Symmetry of objects makes it easy to find the center of mass



following a parabolic path similar to that of a point mass. However, with objects like a baseball bat, where every particle moves differently, predicting motion becomes erratic.

**Ball vs. Baseball Bat**: A ball's symmetrical shape allows for easy identification of its COM, while a baseball bat's motion is complex because *each particle moves independently*. The bat's CM, however, follows a parabolic arc, similar to a ball's motion.



*Fig. 2: Bats' trajectory of CM is not easy to identify due to lack of symmetry* 



![](_page_0_Picture_14.jpeg)

![](_page_1_Picture_0.jpeg)

**Center of Mass (CM)**: The CM is a special point within an object that moves *as if all the object's mass were concentrated there* and all external forces were applied to it.

![](_page_1_Figure_2.jpeg)

For instance, when a bat moves under gravity, its CM follows a parabolic path (Fig 2, above).

If spun on a horizontal table with no net force, the CM moves along a straight line.

![](_page_1_Figure_5.jpeg)

![](_page_1_Picture_7.jpeg)

![](_page_2_Picture_0.jpeg)

# Calculating CM for a System of Particles

 A. For a system of two masses, ma and mb, located at positions xa and xb respectively:

$$X_{cm} = \frac{(m_a X_a + m_b X_b)}{(m_a + m_b)}$$

![](_page_2_Figure_4.jpeg)

Situation 1: When  $m_b = 0$ , the CM coincides with  $x_a$  because the system is reduced to mass  $m_a$  only.

![](_page_2_Figure_6.jpeg)

Situation 2: If ma = mb, the CM lies midway between xa and xb

![](_page_2_Figure_8.jpeg)

![](_page_2_Picture_10.jpeg)

![](_page_3_Picture_0.jpeg)

B. Introducing a third mass  $m_c$  at position  $x_c$ , the CM of the system can be calculated by adding  $m_c x_c$  in the numerator and  $m_c$  in the denominator.

![](_page_3_Figure_2.jpeg)

**Example**: Consider three people of equal mass sitting on a log at positions  $x_a = 2$ ,  $x_b = 10$ , and  $x_c = 12$  meters. What is the CM (see pictorial for solution)

![](_page_3_Figure_4.jpeg)

![](_page_3_Picture_6.jpeg)

![](_page_4_Picture_0.jpeg)

### **General Equation**

A. For a system of n particles spread across the x-axis:

$$x_{cm} = (m_1x_1 + m_2x_2 + m_3x_3 + ... + m_nx_n) / (m_1 + m_2 + ... + m_n)$$

Or if M =  $m_1 + m_2 + ... + m_n$ 

![](_page_4_Figure_5.jpeg)

B. Similar equations can be formulated for y and z coordinates in three-dimensional space, where each coordinate represents the COM of the system.

x-coordinate of COM:	$x_{cm} = (1/M) * \Sigma(m_i x_i)$	(i=1 to n)
y-coordinate of COM:	$y_{cm} = (1/M) * \Sigma(m_i y_i)$	(i=1 to n)
z-coordinate of COM:	$z_{cm} = (1/M) * \Sigma(m_i z_i)$	(i=1 to n)

![](_page_4_Picture_8.jpeg)

![](_page_4_Picture_10.jpeg)

![](_page_5_Picture_0.jpeg)

### Coordinate System Selection

- Choosing a convenient coordinate system can simplify COM calculations. For instance, placing one mass at the origin eliminates certain terms from the equation, streamlining the calculation process.
- The choice of coordinate system does not affect the COM's position relative to the particles; it's a property of the physical particles, not the coordinate system used.

![](_page_5_Figure_4.jpeg)

![](_page_5_Picture_6.jpeg)