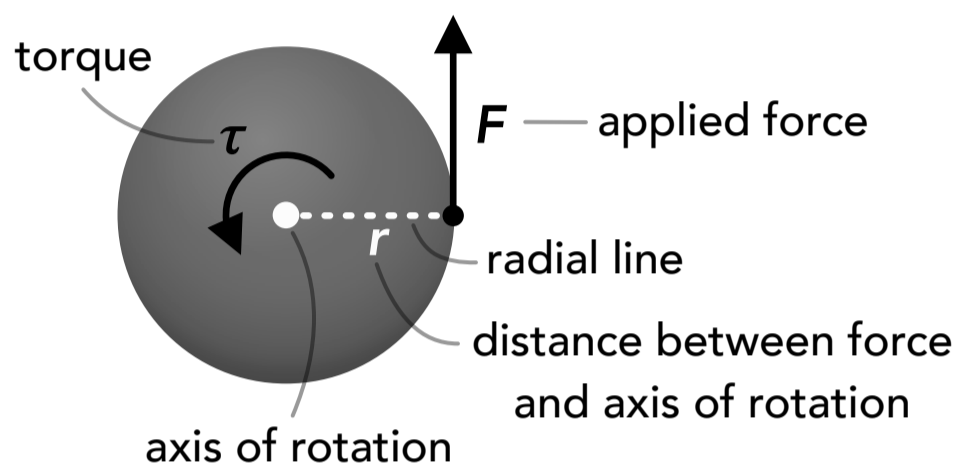


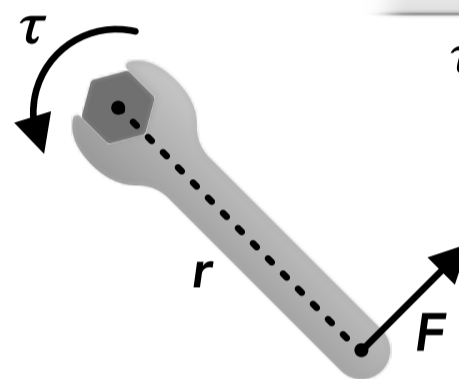
## Torque

- In simple terms, **torque** is like a **rotational force**.
- When a force is applied to an object and that force does not point directly at or away from the object's axis of rotation, that force **generates a torque**.
- If an object is forced to rotate around one point or axis, like a wheel rotating about an axle or a door rotating about a hinge, **that is the axis of rotation**. If an object is free to rotate about any axis, its axis of rotation will pass through its **center of mass**.

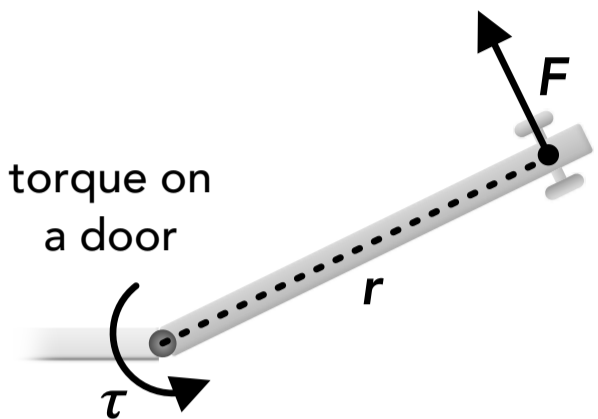
Variables		SI Unit
$\tau$	torque	$\text{N} \cdot \text{m}$
$F$	force	$\text{N}$
$r$	distance from rotation axis	$\text{m}$



torque on a wrench



torque on a door



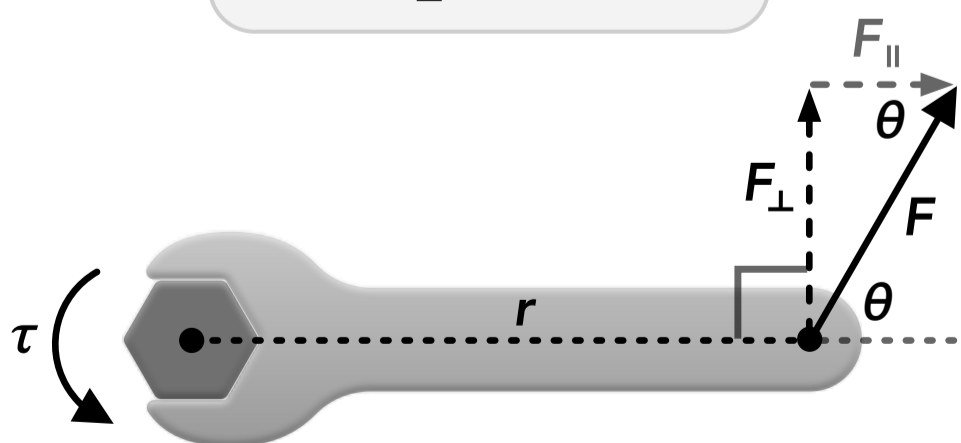
- When you push or pull on a door or a wrench, you're applying a linear force at some distance from the object's axis of rotation and generating a torque on that object which causes it to rotate.

- Torque is represented with the Greek letter  $\tau$  (tau).
- The SI unit of torque is Newton-meters ( $\text{N} \cdot \text{m}$ ) which is given by the equation below.
- Only the component of the force that is **perpendicular** to the radial line between the center of rotation and the point where the force is applied contributes to the torque.
- If the force is not already perpendicular to the radial line, there are two ways to calculate the torque:

Multiply the distance between the axis of rotation and the point where the force is applied ( $r$ ) times the component of the force vector that is perpendicular to the radial line ( $F_{\perp}$ )

Torque

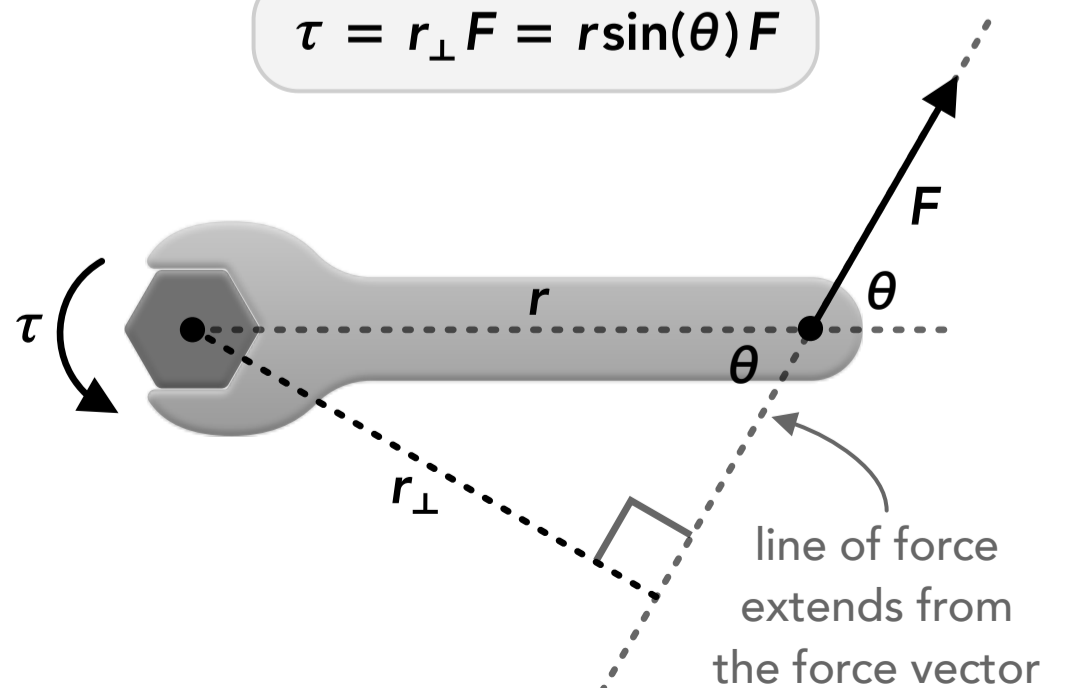
$$\tau = rF_{\perp} = rF\sin(\theta)$$



Multiply the perpendicular distance between the axis of rotation and the line of force ( $r_{\perp}$ ) times the force ( $F$ )

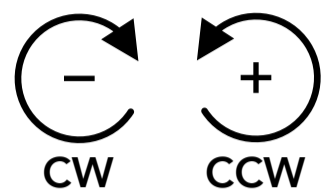
Torque

$$\tau = r_{\perp}F = r\sin(\theta)F$$

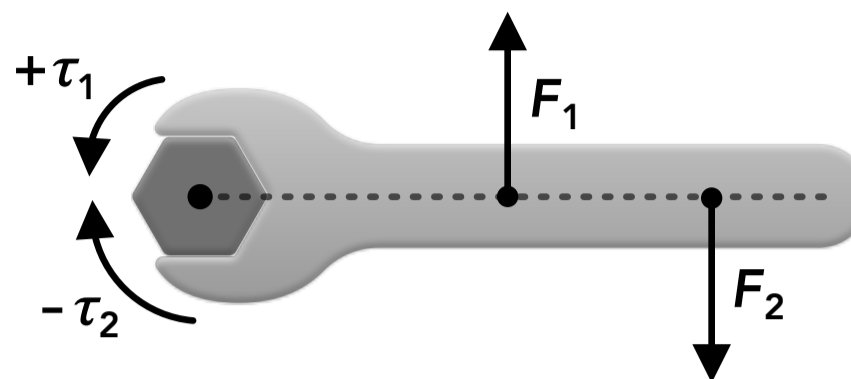


- When looking at the plane of rotation, a torque can either be clockwise (CW) or counterclockwise (CCW).
- **Counterclockwise is the positive direction** using convention, and clockwise is the negative direction, just like in rotational or circular kinematics. This is important when adding several torques to find the net torque.
- The direction of the torque is the direction that the force would cause the object to rotate (CW or CCW).

counterclockwise torque is positive  
clockwise torque is negative



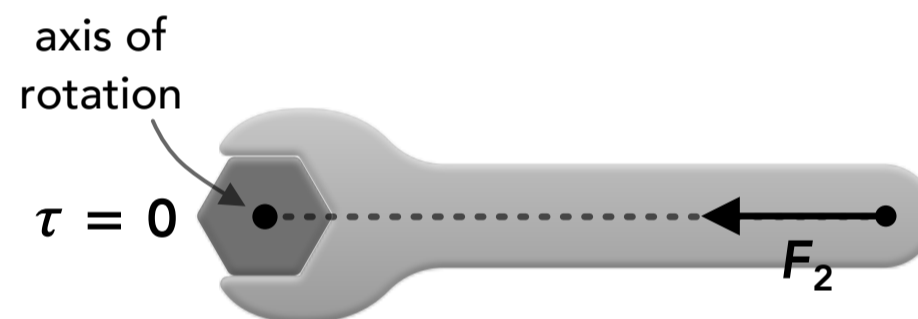
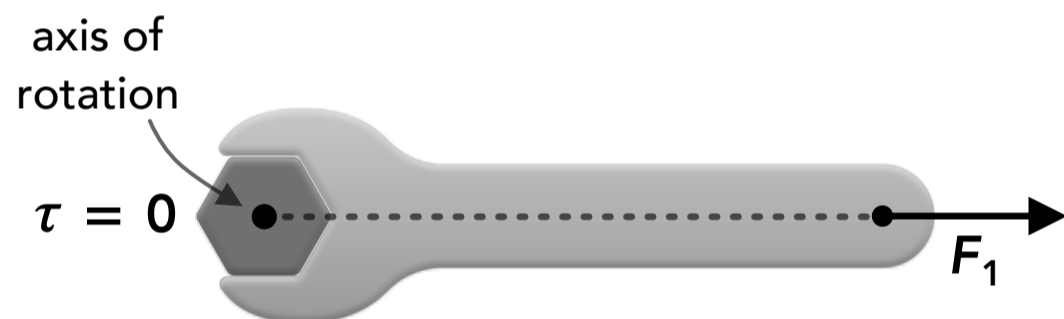
$F_1$  would rotate the wrench counterclockwise  
so it generates a positive torque



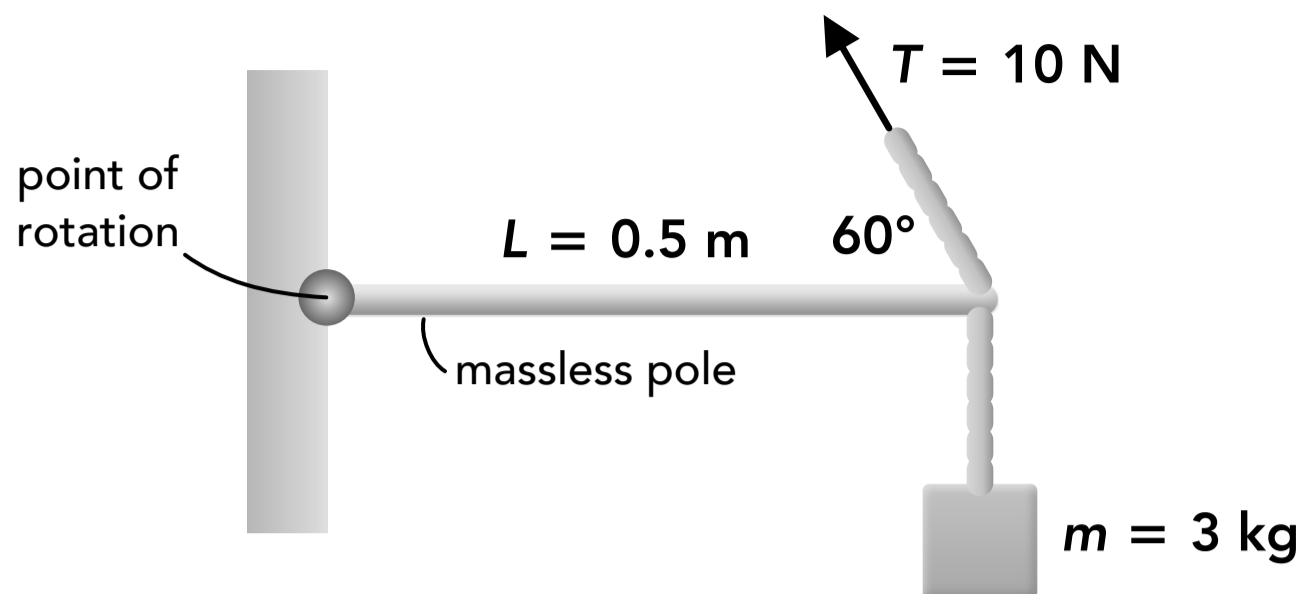
$F_2$  would rotate the wrench clockwise  
so it generates a negative torque

- 
- A force whose line of force passes through the axis of rotation (the force points directly at or away from the axis of rotation) **does not generate a torque** because there is no force component perpendicular to the radial line.

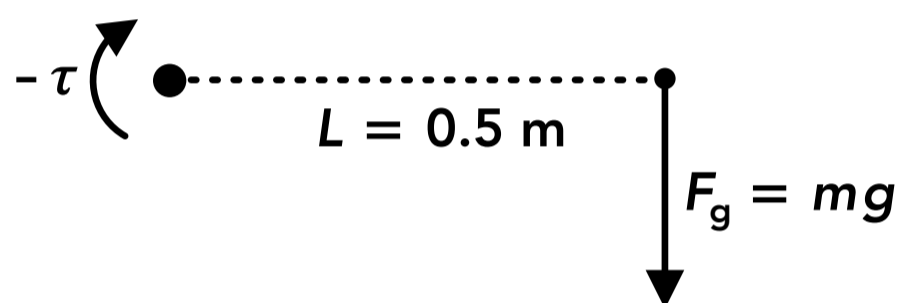
$F_1$  and  $F_2$  do not generate a torque because they act parallel to the radial line  
(directly at or away from the axis of rotation)



Example: A massless pole is pinned to a wall and is free to rotate about its left end. At the right end of the pole a mass is hanging straight down and a rope pulls the pole up with a tension force at an angle. What are the torques generated by the hanging mass and the tension force about the point of rotation on the left?

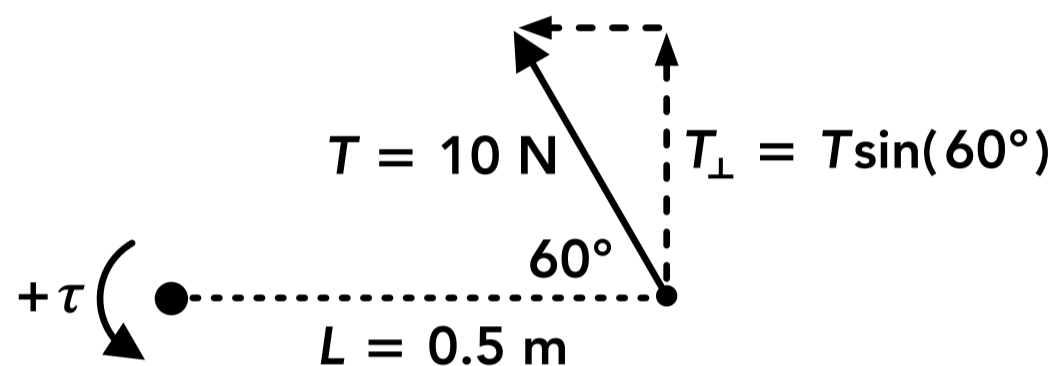


Torque from hanging mass:



$$\begin{aligned} \tau &= rF_{\perp} \\ \tau &= (L)(mg) \\ \tau &= (0.5 \text{ m})(3 \text{ kg})(9.8 \text{ m/s}^2) \\ \tau &= 14.7 \text{ Nm (magnitude of torque)} \\ &\downarrow \\ \tau &= -14.7 \text{ Nm} \\ &\text{torque is clockwise so it's negative} \end{aligned}$$

Torque from upper rope:



$$\begin{aligned} \tau &= rF_{\perp} \\ \tau &= (L)(T\sin(60^{\circ})) \\ \tau &= (0.5 \text{ m})(10 \text{ N})\sin(60^{\circ}) \\ \tau &= 4.3 \text{ Nm (magnitude of torque)} \\ &\downarrow \\ \tau &= 4.3 \text{ Nm} \\ &\text{torque is counterclockwise so it's positive} \end{aligned}$$