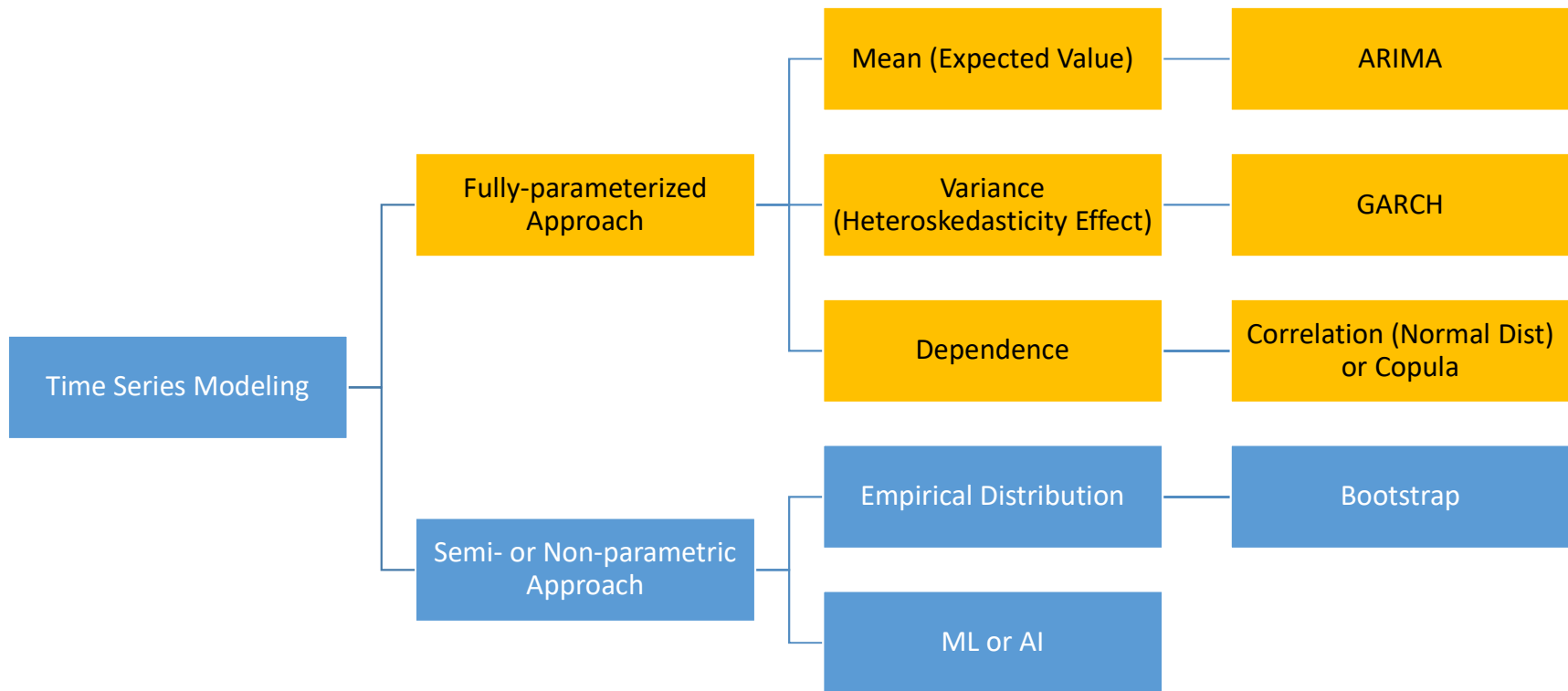




Copula & Time Series Modeling for Risk Analysis Application

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My Approach to Time Series Modeling



Mean Equation

- The mean equation of an univariate time series x_t can be described by the process

$$x_t = E(x_t | F_{t-1}) + \varepsilon_t$$

- where $E(\cdot | \cdot)$ denotes the conditional expectation operator, F_{t-1} the information set at time $t - 1$, and ε_t the innovations of the time series.

ARMA mean equation

- The ARMA(m,n) process of autoregressive order m and moving average order n can be described as

$$x_t = \mu + \sum_{i=1}^m a_i x_{t-i} + \sum_{j=1}^n b_j \varepsilon_{t-j} + \varepsilon_t ,$$

- with mean μ , autoregressive coefficients a_i and moving average coefficients b_i .

ARIMA mean equation

- Let Y denote the *original* series
- Let y denote the *differenced* (stationarized) series

No difference $(d=0)$: $y_t = Y_t$

First difference $(d=1)$: $y_t = Y_t - Y_{t-1}$

Second difference $(d=2)$: $y_t = (Y_t - Y_{t-1}) - (Y_{t-1} - Y_{t-2})$
$$= Y_t - 2Y_{t-1} + Y_{t-2}$$

ARIMA mean equation

$$\hat{y}_t = \underbrace{\mu}_{\text{constant}} + \underbrace{\phi_1 y_{t-1} + \dots + \phi_p y_{t-p}}_{\text{AR terms (lagged values of } y)}$$

By convention, the
AR terms are + and
the MA terms are –

$$- \underbrace{\theta_1 e_{t-1} \dots - \theta_q e_{t-q}}_{\text{MA terms (lagged errors)}}$$

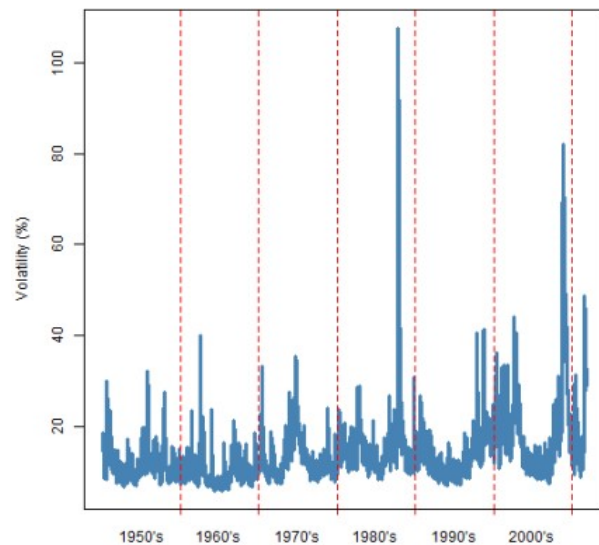
Not as bad as it looks! Usually $p+q \leq 2$ and
either $p=0$ or $q=0$ (pure AR or pure MA model)

ARIMA models we've already met

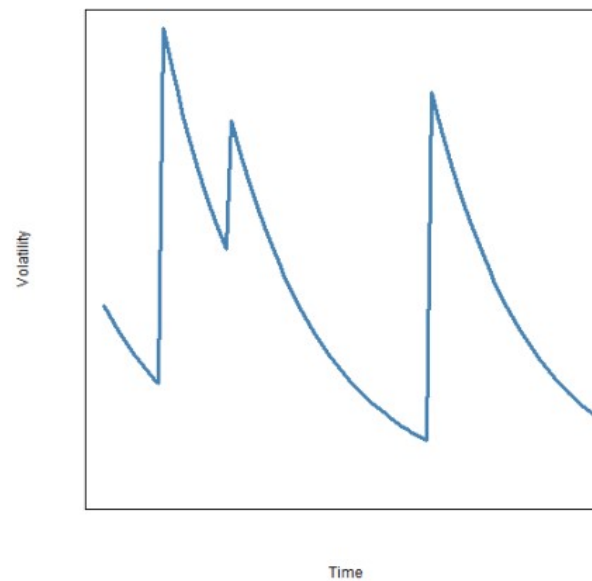
- $\text{ARIMA}(0,0,0)+c$ = mean (constant) model
- $\text{ARIMA}(0,1,0)$ = RW model
- $\text{ARIMA}(0,1,0)+c$ = RW with drift model
- $\text{ARIMA}(1,0,0)+c$ = regress Y on Y_{LAG1}
- $\text{ARIMA}(1,1,0)+c$ = regr. Y_{DIFF1} on $Y_{\text{DIFF1_LAG1}}$
- $\text{ARIMA}(2,1,0)+c$ = " " plus $Y_{\text{DIFF_LAG2}}$ as well
- $\text{ARIMA}(0,1,1)$ = SES model
- $\text{ARIMA}(0,1,1)+c$ = SES + constant linear trend
- $\text{ARIMA}(1,1,2)$ = LES w/ damped trend (leveling off)
- $\text{ARIMA}(0,2,2)$ = generalized LES (including Holt's)



Variance Equation: GARCH



=



+

Volatility
Noise + MA
Component

Variance Equation: GARCH

- The mean equation does not take into account heteroskedastic effects typically observed in financial time series. Engle [1982] introduced the Autoregressive Conditional Heteroskedastic model, named ARCH, later generalised by Bollerslev [1986], named GARCH.

$$\begin{aligned}\varepsilon_t &= Z_t \sigma_t , \\ Z_t &\sim \mathcal{D}_\vartheta(0, 1) , \\ \sigma_t^2 &= \omega + \sum_{i=1}^p \alpha_i \varepsilon_{t-i}^2 + \sum_{j=1}^q \beta_j \sigma_{t-j}^2 ,\end{aligned}$$

Variance Equation: GARCH

- Ding [1993] introduced the APARCH(p,q) variance that can be expressed as

$$\begin{aligned}\varepsilon_t &= Z_t \sigma_t, \\ Z_t &\sim \mathcal{D}_\vartheta(0, 1), \\ \sigma_t^\delta &= \omega + \sum_{i=1}^p \alpha_i (|\varepsilon_{t-i}| - \gamma_i \varepsilon_{t-i})^\delta + \sum_{j=1}^q \beta_j \sigma_{t-j}^\delta,\end{aligned}$$

- where $\delta > 0$ and $-1 < \gamma_i < 1$. This model adds the flexibility of a varying exponent with an asymmetry coefficient γ_i to take the leverage effect into account and the varying power δ to consider the Taylor effect.



Multivariate GARCH: DCC-GARCH

The Dynamic Conditional Correlation (DCC-) GARCH belongs to the class "Models of conditional variances and correlations" as discussed in Section 3.3. It was introduced by Engle and Sheppard in 2001 [11]. The idea of the models in this class is that the covariance matrix, \mathbf{H}_t , can be decomposed into conditional standard deviations, \mathbf{D}_t , and a correlation matrix, \mathbf{R}_t . In the DCC-GARCH model both \mathbf{D}_t and \mathbf{R}_t are designed to be time-varying.

Suppose we have returns, \mathbf{a}_t , from n assets with expected value 0 and covariance matrix \mathbf{H}_t . Then the Dynamic Conditional Correlation (DCC-) GARCH model is defined as:

$$\mathbf{r}_t = \boldsymbol{\mu}_t + \mathbf{a}_t \quad (24)$$

$$\mathbf{a}_t = \mathbf{H}_t^{1/2} \mathbf{z}_t \quad (25)$$

$$\mathbf{H}_t = \mathbf{D}_t \mathbf{R}_t \mathbf{D}_t \quad (26)$$

Notation:

\mathbf{r}_t :	$n \times 1$ vector of log returns of n assets at time t .
\mathbf{a}_t :	$n \times 1$ vector of mean-corrected returns of n assets at time t , i.e. $E[\mathbf{a}_t]=0$. $\text{Cov}[\mathbf{a}_t] = \mathbf{H}_t$.
$\boldsymbol{\mu}_t$:	$n \times 1$ vector of the expected value of the conditional \mathbf{r}_t .
\mathbf{H}_t :	$n \times n$ matrix of conditional variances of \mathbf{a}_t at time t .
$\mathbf{H}_t^{1/2}$:	Any $n \times n$ matrix at time t such that \mathbf{H}_t is the conditional variance matrix of \mathbf{a}_t . $\mathbf{H}_t^{1/2}$ may be obtained by a Cholesky factorization of \mathbf{H}_t .
\mathbf{D}_t :	$n \times n$, diagonal matrix of conditional standard deviations of \mathbf{a}_t at time t .
\mathbf{R}_t :	$n \times n$ conditional correlation matrix of \mathbf{a}_t at time t .
\mathbf{z}_t :	$n \times 1$ vector of iid errors such that $E[\mathbf{z}_t]=0$ and $E[\mathbf{z}_t \mathbf{z}_t^T] = \mathbf{I}$.

