



Algebraic Fractions

Simplify rational expressions, including factorising, cancelling, algebraic division

Partial Fractions

Decompose rational functions into partial fractions

Use partial fractions to integrate, differentiate or expand rational functions



Binomial Expansion

- Use the binomial expansion $(a + bx)^n$ for fractional and negative values of n
- Be aware that the expansion is valid for $|\frac{bx}{a}| < 1$

Notation & Language of Series

- Work with sequences given by a formula for the n th term
- Work with sequences generated by a simple relation of the form $x_{n+1} = f(x_n)$
- Identify increasing sequences, decreasing sequences and periodic sequences
- Understand and use sigma notation for sums of series

Arithmetic Series & Geometric Series

- Use the formula for the n th term and the sum to n terms of an arithmetic sequence
- Use the formula for the n th term and the sum to n terms of a finite geometric sequence
- Use the formula for the sum to infinity of a convergent geometric series where $|r| < 1$
- Use sequences and series in modelling, eg amounts paid into saving schemes



Change of Sign Argument

- Locate roots of $f(x) = 0$ by considering changes of sign of $f(x)$ in an interval of x
- Understand that change of sign methods can fail if $f(x)$ is not continuous or roots > 1

Simple Iterative Methods

- Use an iteration in the form $x_{n+1} = f(x_n)$ to find a root to the equation $x = f(x)$
- Know that the iteration $x_{n+1} = g(x_n)$ converges to a root at $x = a$ if $|g'(a)| < 1$
- Draw cobweb and staircase diagrams to illustrate simple iterative methods

Newton-Raphson

- Solve equations using the Newton-Raphson method and other recurrence relations
- Understand the Newton-Raphson fails if the initial value coincides with a stationary point

Small Angle Approximations

- Understand and use the small angle approximations for **sine**: $\sin \theta \approx \theta$
- Understand and use the small angle approximation for **cosine**: $\cos \theta \approx 1 - \frac{\theta^2}{2}$
- Understand and use the small angle approximation for **tangent**: $\tan \theta \approx \theta$



Functions

- Understand and use composite functions, inverse functions and their graphs
- Understand that a function is a one-one or many-one mapping
- Understand and find the domain and range of functions
- Understand that $y = f^{-1}(x)$ is a reflection of the graph $y = f(x)$ in the line $y = x$
- Use functions in modelling, understanding the limitations and refinements

Modulus Equations & Inequalities

- Sketch the graphs of $y = |ax + b|$
- Use the graph to solve modulus equations and inequalities, eg $y = |2x - 1|$
- Use relations such as $|a| = |b| \Leftrightarrow a^2 = b^2$ and $|x - a| < b \Leftrightarrow a - b < x < a + b$

Graph Transformations

- Apply multiple transformations to functions of $x^2, x^3, x^4, \frac{1}{x}, \frac{1}{x^2}, |x|, \sin x, \cos x, \tan x, e^x, a^x$
- Sketch the graphs of $y = |f(x)|$ and $y = |f(-x)|$ given $y = |f(x)|$

Parametrically Defined Functions

- Understand and use the parametric equations of curves
- Convert between Cartesian and parametric forms
- Use parametric equations in modelling in a variety of contexts



Vectors in 3 Dimensions

- Use vectors in 3 dimensions, in the form of column vectors and as **i**, **j** and **k** unit vectors
- Find the magnitude and direction of 3D vectors
- Use scalar multiplication and vector addition for 3D vectors

Formulae for Sectors

- Work with radian measure, including arc length ($s = r\theta$) and area of sector ($\frac{1}{2}r^2\theta$)



Reciprocal Trig Functions

- Know and use exact values of **sin**, **cos** and **tan** for $0, \frac{\pi}{6}, \frac{\pi}{4}, \frac{\pi}{3}, \frac{\pi}{2}, \pi$ and multiples
- Understand and use the definitions of **secant**, **cosecant** and **cotangent**
- Understand the graphs, ranges and domains of the reciprocal trig functions

Pythagorean Identities

- Understand and use $\sec^2 \theta = 1 + \tan^2 \theta$ and $\operatorname{cosec}^2 \theta = 1 + \cot^2 \theta$

Addition Formulae

- Understand and use the formulae $\sin(A \pm B)$, $\cos(A \pm B)$ and $\tan(A \pm B)$
- Understand the geometrical proofs for these formulae

Double/Half Angle Formulae

- Understand and use double angle formulae for **sin**, **cos** and **tan**

Harmonic Form $R \cos(x + a)$

- Convert the expression $a \cos \theta + b \sin \theta$ into the form $r \cos(\theta \pm \alpha)$ or $r \sin(\theta \pm \alpha)$
- Solve equations such as $a \cos \theta + b \sin \theta = c$ in a given interval

Inverse Trig Functions

- Understand and use the definitions of **arcsin**, **arccos** and **arctan**
- Understand the graphs, ranges and domains of the inverse trig functions



Increasing, Decreasing, Concave & Convex Graphs

- Use the second derivative to determine if a graph is convex or concave over an interval
- Use the second derivative to find point(s) of inflection of a graph

The Derivatives

- Differentiate e^{kx} , a^{kx} , $\ln x$, $\sin kx$, $\cos kx$, $\tan kx$ and related multiples
- Show differentiation from first principles for $\sin x$ and $\cos x$

The Chain Rule

- Understand and use the chain rule to differentiate functions
- Use connected rates of changes in models
- Differentiate parametric functions to find the equations of tangents and/or normals

The Product & Quotient Rules

- Understand and use the quotient rule and the product rule to differentiate functions
- Differentiate $\operatorname{cosec} x$, $\cot x$ and $\sec x$
- Differentiate functions such as $2x^4 \sin x$, $\frac{e^{3x}}{x}$, $\cos^2 x$ and $\tan^2 2x$

Implicit Differentiate and Parametric Differentiation

- Differentiate functions in the form $x = f(y)$, eg $x = \sin y$, then use $\frac{dy}{dx} = 1 \div \left(\frac{dx}{dy}\right)$
- Differentiate simple parametrically defined functions



Integrate Fractions, Exponentials and Trig

- Be able to integrate e^{kx} , $\frac{1}{x}$, $\sin kx$, $\cos kx$ and related multiples

Integration by Substitution

- Carry out simple cases of integration by substitution
- Understand that integration by substitution is the inverse of the chain rule
- Find and use an appropriate substitution for integration by substitution
- Recognise an integrand of the form $\frac{k f'(x)}{f(x)}$

Parametric Integration

- Evaluate the area of a region bounded by a parametrically defined curve

Integration by Parts

- Carry out simple cases of integration by parts
- Understand that integration by parts is the inverse of the product rule
- Use more than one application of integration by parts, eg for $x^2 \sin x$
- Apply integration by parts to the integral $\ln x$ and related functions

Form & Solve Differential Equations

- Evaluate the solution of simple first order differential equations with separate variables
- Interpret the solution of a differential equation in context, eg kinematics



Proof by Contradiction

Use proof by contradiction to prove the irrationality of $\sqrt{2}$

Use proof by contradiction to prove the infinity of primes

Apply proof by contradiction to unfamiliar proofs



Product Moment Correlation Coefficient

- Know that the product moment correlation coefficient r satisfies $|r| \leq 1$
- Know that if $r = \pm 1$ all of the data points lie on a straight line
- Calculate r using a calculator (Edexcel)



Independent Events

- Use set notation to describe events
- Use $P(B | A) = P(B)$, $P(A | B) = P(A)$ when A and B are independent events
- Use $P(A \cap B) = P(A)P(B)$ when A and B are independent events

Conditional Probability

- Understand and use conditional probability and the conditional probability formula
- Use conditional probability in tree diagrams, Venn diagrams and two-way tables
- Understand and use $P(A') = 1 - P(A)$
- Understand and use $P(A \cup B) = P(A) + P(B) - P(A \cap B)$
- Understand and use $P(A \cap B) = P(A)P(B | A)$
- Model with probability, including critiquing assumptions made and their effect



Key Features of a Normal Distribution

- Know the shape and symmetry of the normal distribution
- Know that the points of inflection are at $x = \mu \pm \sigma$
- Understand and use the notation $X \sim N(\mu, \sigma^2)$
- Know approximately two-thirds of the data lies in the range $\mu \pm \sigma$
- Know approximately 95 % of the data lies in the range $\mu \pm 2\sigma$
- Know almost all data lies in the range $\mu \pm 3\sigma$

Using the Normal Distribution

- Understand and use the normal distribution as a model
- Find probabilities using the normal distribution by using a calculator
- Be able to recognise when the binomial or normal model may not be appropriate
- Be able to link the normal distribution to histograms

Using the Normal to Approximate the Binomial

- Know when n is large, $p \approx 0.5$, $B(n, p)$ can be approximated by $N(np, np[1 - p])$
- Apply a continuity correction to this approximation (Edexcel)



Hypothesis Testing for the Mean of a Population

- Conduct a statistical hypothesis test for the mean of a Normal distribution
- Know that if $X \sim N(\mu, \sigma^2)$ then $\bar{x} \sim N(\mu, \frac{\sigma^2}{n})$
- Interpret the results of the hypothesis test in context

Hypothesis Testing for Zero Correlation

- Be able to interpret a correlation coefficient given a p -value or critical value
- State hypotheses in terms of ρ where ρ = the population correlation coefficient



Projectiles

Model motion under gravity in a vertical plane using vectors

Derive formulae for time of flight, range, and greatest height



2D Variable Acceleration



Differentiation and integration of vectors with respect to time



Friction

- Understand and use the coefficient of friction, μ
- Understand that, for a body in motion, $F = \mu R$
- Understand that, for a body at equilibrium, $F \leq \mu R$
- Solve problems involving a body on a rough surface

Resolving Forces

- Understand and use the term resultant as applied to 2+ forces acting at a point
- Understand and use Newton's second law when forces need to be resolved
- Understand and use Newton's third law when forces need to be resolved

Motion on an Inclined Plane

- Use the addition of forces and resultant forces to model motion on an inclined plane



Moments

- Calculate the moment of a force about an axis through a point in the plane of the body
- Understand that when a rigid body is in equilibrium the resultant moment is zero
- Apply moments to simple static problems, eg ladders, uniform/non-uniform rods, laminas